

**DOE-FIU Cooperative Agreement Annual Research Review – FIU Year 1** 

# Robotic Application of Coatings in the SRNL H-CAEX

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Advancing the research and academic mission of Florida International University

#### **Overall Needs:**

- Corrosion mitigation within H-Canyon Exhaust Tunnel
- Application system that can withstand environmental conditions:
  - 30 MPH or higher winds
  - Concrete debris
  - High humidity and moisture levels
  - Presence of radiation and nitric acid vapor

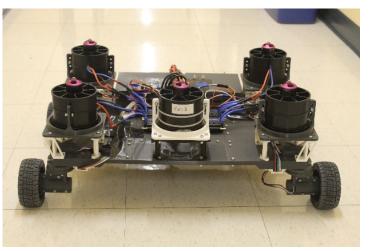
#### **Objectives:**

- Develop a robust robotic system with vertical wall traversal capability
  - Transition capabilities between horizontal and vertical surfaces
  - Robust surface adhesion mechanism via EDF thrust
  - Payload capacity for application mechanism

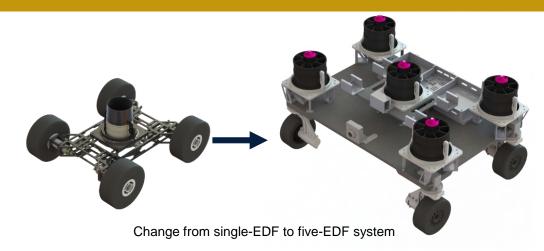


#### **FIU Year 1 Highlights:**

- Platform expansion to five-EDF unit
  - Larger platform size for improved potential applicator surface area
  - Omnidirectional drive allows for forward/backward and strafing motions
  - Slide-in drive units for ease of maintenance
  - Initial interlocking 3D-printed chassis design

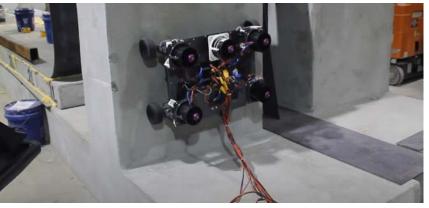


Constructed five-EDF system





Slide-in drive units



System climbing vertical concrete wall for testing

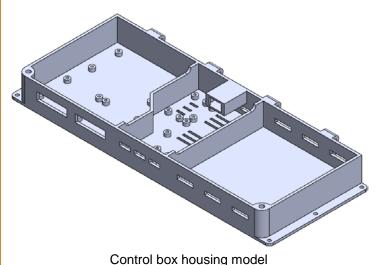


#### **FIU Year 1 Highlights:**

- Control box prototype developed
  - Housing designed and printed to accommodate majority of electronic components
  - Contains system-on-a-chip, microcontroller, motor controllers, and power distribution
  - Designed to operate different iterative platform configurations via ROS

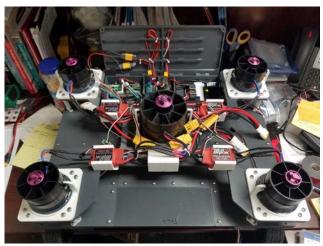


Populated control box





Printed control box housing



Control box installed on platform

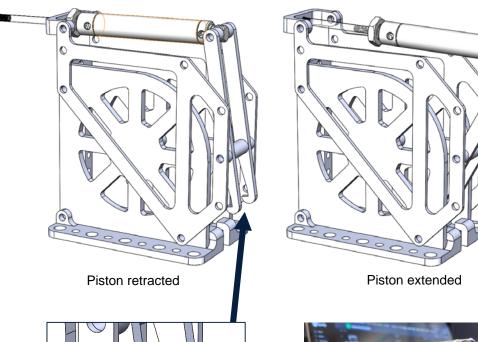


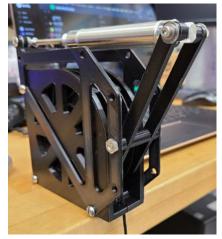
#### **FIU Year 1 Highlights:**

- Testing safety harness for platform developed
  - Manually operated safety harness to catch platform in case of failure during testing
  - Pneumatic system with mechanical catch for reliable operation
  - Two units constructed to work in conjunction with each other









Closer view of catches

Constructed unit



#### **Future work**

- Continue iterative development of climbing platform
- Complete manufacturing of carbon fiber chassis
- Blade degradation literature review
- Debris ingestion study on EDF performance









- DOE-FIU Science and Technology Workforce Development Program
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## Thank You. Questions?