

DOE-FIU Cooperative Agreement Annual Research Review

PROJECT 3 TASK 2 SUBTASK 2.5 Digitalization of Decommissioning



Subtask 2.5 Digitalization in Decommissioning

Introduction:

- Decommissioning Process by which a nuclear facility is irreversibly and completely/partially closed, either when the facility reaches the end of its operation license or when the environment becomes too hazardous to operate safely
- Digitalization of Decommissioning –
 Alteration of the decommissioning process via the implementation of mechanical/electrical/computer systems in order to increase efficiency and prevent injury and/or loss of life











Subtask 2.5: Digitalization in Decommissioning

Research Highlights & Accomplishments:

Main objectives:

- Investigate use of robotic systems/LiDAR systems for D&D application
- Integrate radiation sensors into robotic/LiDAR system for radiation mapping feature
- Develop 3D Parametric Models and facility walkdowns
- Incorporate 3D Parametric Models into BIM models









Subtask 2.5 Digitalization in Decommissioning

Research Highlights & Accomplishments:

Robotic/LiDAR Systems:

- Boston Dynamics Spot robot dog and Trimble X7 3D Laser Scanner
- Continuous testing into technical capabilities
 - Robot test deployments and difficult terrain navigation testing with and without Trimble payload
 - 3D point cloud data collected through Trimble X7 refined and post-processed for walkdowns

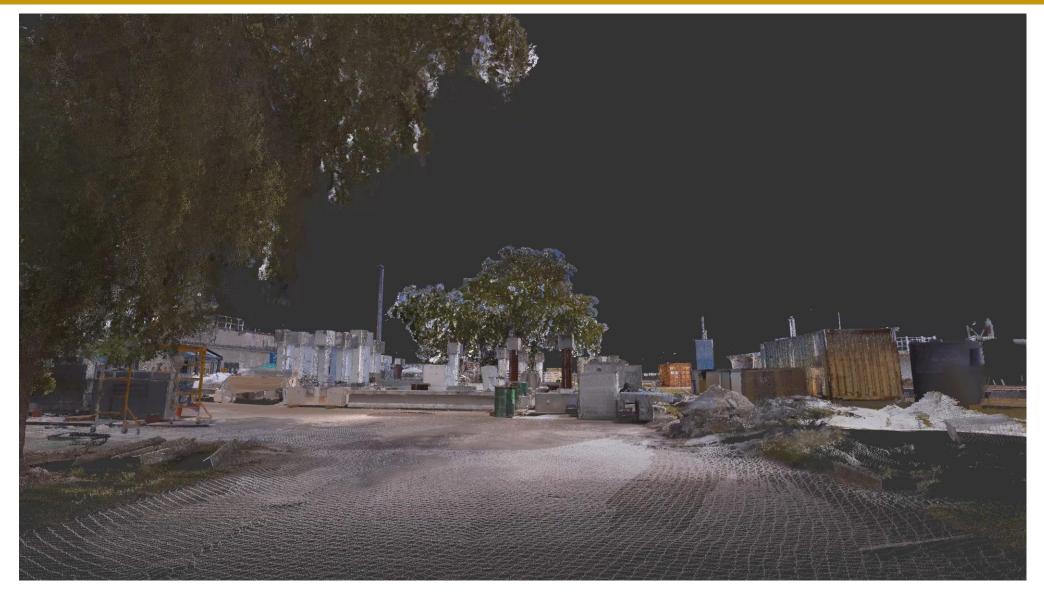
Radiation Mapping/Walkdowns:

- Integration of radiation mapping tools to Spot/Trimble system undergoing research
 - Initial testing undergoing fine-tuning,
 physical device installed using temporary
 parts
- Refinement/post-processing of 3D scans allow for development of 3D walkdowns





Subtask 2.5: Digitalization in Decommissioning





Facility Walkdown



Subtask 2.5: Digitalization in Decommissioning

Research Highlights & Accomplishments:











